

Chp 2 Matrices and System of Linear Equations

2.1: Matrices: Definition and Notation

Def<sup>n</sup> An  $m \times n$  (read "m by n") matrix is a rectangular array of numbers arranged in  $m$  horizontal rows and  $n$  vertical columns.

e.g.  $A = \begin{pmatrix} 9 & 3 & -2 \\ 10 & 0 & -1 \\ -5 & 7 & 4 \end{pmatrix}$  is a  $3 \times 3$  matrix.  
 (1st row circled, 3rd col circled)

$$B = \begin{pmatrix} -1 & 0 \\ -5 & 2 \\ 7 & 14 \\ 2 & 1 \end{pmatrix} \text{ is a } 4 \times 2 \text{ matrix}$$

The expression  $m \times n$  is called the size of the matrix.

The entry in the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column of a matrix  $A$  is denoted by  $a_{ij}$ .

e.g.  $a_{13} = -2$   $a_{11} = 9$   
 $b_{42} = 1$

Two matrices  $A$  and  $B$  are equal written  $A=B$  if they have the same size and  $a_{ij} = b_{ij}$  for all possible values of  $i$  and  $j$ .

e.g.  $(1 \ 2) = (1 \ 1+1)$

Def<sup>n</sup> A  $1 \times n$  matrix is called a row  $n$ -vector

An  $n \times 1$  matrix is called a column  $n$ -vector

The entries of a row or a column  $n$ -vector are called the components of the vector.

e.g.  $a = (-2 \ \frac{1}{3} \ 5)$  is a row 3-vector

$b = \begin{pmatrix} 3 \\ 0 \\ -1 \\ -1 \end{pmatrix}$  is column 4-vector  
 $a_1 = -2$   $a_2 = \frac{1}{3}$   $a_3 = 5$

$b_2 = 0$

If  $a_1 = (1 \ 2 \ 3)$  and  $a_2 = (4 \ 5 \ 6)$  then  $\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$

similarly if  $b_1 = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$   $b_2 = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$   $b_3 = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$   
 $(b_1 \ b_2 \ b_3) = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$

Def<sup>n</sup> If we interchange the rows and columns in an  $m \times n$  matrix  $A$ , we obtain an  $n \times m$  matrix called the transpose of  $A$ , denoted  $A^T$ .

In index notation

$a^T_{ij} = a_{ji}$   $A = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$   $A^T = (1 \ 2)$

$B = \begin{pmatrix} 5 & 0 \\ -1 & 2 \end{pmatrix}$   $B^T = \begin{pmatrix} 5 & -1 \\ 0 & 2 \end{pmatrix}$

Def<sup>n</sup> An  $n \times n$  matrix is called a square matrix. If  $A$  is a square matrix, the entries  $a_{ii}$  are called the diagonal entries.

e.g.  $\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$  Diagonal entries

The sum of all diagonal entries of an  $n \times n$  matrix  $A$  is called the trace of  $A$ , denoted by  $\text{tr}(A)$ .

$\text{tr}(A) = a_{11} + a_{22} + \dots + a_{nn}$

Def<sup>n</sup> An  $n \times n$  matrix is said to be lower triangular if  $a_{ij} = 0$  whenever  $i < j$  and it is called upper triangular if  $a_{ij} = 0$  whenever  $i > j$ . Finally if  $a_{ij} = 0$  whenever  $i \neq j$ ,  $A$  is called diagonal.

e.g.  $\begin{pmatrix} 5 & 2 & 4 \\ 0 & 1 & 6 \\ 0 & 0 & 3 \end{pmatrix}$  is upper triangular

$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$  is diagonal.  
 $a_{11} = 0$   $a_{22} = 1$

$\begin{pmatrix} 10 & 0 & 0 \\ -2 & 3 & 0 \\ 4 & 5 & 6 \end{pmatrix}$  is lower triangular

$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  is upper and lower triangular and diagonal.

For a diagonal matrix  $D = (d_{ij})$  we sometimes use the notation

$D = \text{diag}(d_{11}, d_{22}, \dots, d_{nn})$

e.g.  $\begin{pmatrix} 5 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 10 \end{pmatrix} = \text{diag}(5, 3, 10)$

Def<sup>n</sup>  $A$  is called a symmetric matrix if  $A = A^T$

It is called skew-symmetric if

$$A = -A^T$$

e.g.  $\begin{pmatrix} -7 & 2 & 3 \\ 2 & 4 & -5 \\ 3 & -5 & 0 \end{pmatrix}$  is symmetric

e.g.  $\begin{pmatrix} 0 & 5 & 4 \\ -5 & 0 & 6 \\ -4 & -6 & 0 \end{pmatrix}$  is skew-sym.

Note that for skew-symmetric matrices diagonal entries have to be 0.

Say  $A$  is skew-sym. Prove that diagonal entries have to be 0

Pf We want to show that for all possible values of  $i$ ,  $a_{ii} = 0$

$$a_{ii} = -a_{ii} = -a_{ii}$$

$$2a_{ii} = 0 \Rightarrow a_{ii} = 0$$

Def<sup>n</sup> An  $m \times n$  matrix function is a rectangular array with  $m$  rows and  $n$  columns whose elements are functions of a real variable  $t$ .

e.g.  $A(t) = \begin{pmatrix} 5 & e^t & \cosh(t) - 2t \\ t^2 + 5 & \ln t & \sin t \\ t & & \end{pmatrix}$

Def<sup>n</sup> An  $n \times 1$  matrix function is called a column  $n$ -vector function

e.g.  $\begin{pmatrix} t^2 \\ \ln(3+t) \end{pmatrix}$

## 2.2 Matrix Algebra

If  $A = (a_{ij})$ ,  $B = (b_{ij})$  are both  $m \times n$  matrices, we set

$$A+B = (a_{ij} + b_{ij})$$

e.g.  $\begin{pmatrix} 5 & 4 & 3 \\ 1 & 2 & 7 \end{pmatrix} + \begin{pmatrix} 10 & 20 & 30 \\ 40 & 50 & 60 \end{pmatrix}$

$$= \begin{pmatrix} 15 & 24 & 33 \\ 41 & 52 & 67 \end{pmatrix}$$

$\begin{pmatrix} 3 & 2 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 10 \\ -7 \\ 3 \end{pmatrix}$  is undefined!

Properties •  $A+B = B+A$   
(addition is commutative)

•  $A+(B+C) = (A+B)+C$   
(addition is associative)

By a scalar, we mean a real or complex number.

Def<sup>n</sup> If  $A$  is an  $m \times n$  matrix and  $c$  is a scalar we set

$$cA = (c a_{ij}), \text{ the scalar multiplication.}$$

e.g.  $10 \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} = \begin{pmatrix} 10 & 20 & 30 \\ 40 & 50 & 60 \end{pmatrix}$

$i \begin{pmatrix} 3+i & i \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 3i-1 & -1 \\ 0 & i \end{pmatrix}$

Properties:

- $1A = A$  (unit property)
- $s(A+B) = sA + sB$  distributivity
- $(s+t)A = sA + tA$  //

•  $s(tA) = (st)A = (ts)A = t(sA)$   
associativity

Def<sup>n</sup> If  $A = (a_{ij})$ ,  $B = (b_{ij})$  have the same size, set

$$A-B = A + (-1)B$$

(equivalently  $A-B = (a_{ij} - b_{ij})$ )

e.g.  $\begin{pmatrix} 10 & 20 \\ 30 & 40 \end{pmatrix} - \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 9 & 18 \\ 27 & 36 \end{pmatrix}$

$$\begin{pmatrix} 5 & 7 \\ 3 & 2 \end{pmatrix} - \begin{pmatrix} 5 & 7 \\ 3 & 2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

called the  $2 \times 2$  zero matrix

We denote the  $m \times n$  0 matrix by  $O_{m \times n}$  or simply by  $O$  if dimensions are clear.

Properties •  $A+O = A$

•  $A-A = O$

•  $0A = O$

↑ scalar 0      ↑ 0 matrix of size = size of A

Def<sup>n</sup> If  $a$  and  $b$  are either row or column  $n$ -vectors with components  $a_1, a_2, \dots, a_n$  and  $b_1, b_2, \dots, b_n$  respectively, then their dot product, denoted  $a \cdot b$  is the number  $a_1 b_1 + a_2 b_2 + \dots + a_n b_n$

$$\text{e.g. } (1 \ 2 \ 3) \cdot (10 \ 0 \ -10)$$

$$= 1(10) + 2(0) + 3(-10)$$

$$= 10 + 0 - 30 = -20$$

or

$$\begin{pmatrix} 3 & -1 \\ 2 & 5 \end{pmatrix} = -3 + 10 = 7$$

Remark: We only take dot product of two row vectors or two column vectors.

If  $x = (x_1 \ x_2 \ \dots \ x_n)$

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \text{ then}$$

$\Leftrightarrow$  their matrix product  $xy$  is the  $1 \times 1$  matrix

$$xy = (x_1 \ \dots \ x_n) \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = (x_1 y_1 + x_2 y_2 + \dots + x_n y_n)$$